# The Quartic Integrability and Long Time Existence of Water Waves in 2d 

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## The gravity water wave equations

We assume that

- the air density is 0 , the fluid density is $1 .(0,-g)$ is the gravity.
- the fluid is inviscid, incompressible, irrotational,
- the surface tension is zero.

Let $\Omega(t)$ be the fluid domain, $\partial \Omega(t)$ be the interface at time $t$.
The motion of the fluid is described by

$$
\left\{\begin{array}{l}
\mathbf{v}_{t}+(\mathbf{v} \cdot \nabla) \mathbf{v}=(\mathbf{0},-g)-\nabla P \quad \text { in } \Omega(t) \\
\operatorname{div} \mathbf{v}=0, \quad \operatorname{curl} \mathbf{v}=0, \quad \text { in } \Omega(t)  \tag{1}\\
P=0, \quad \text { on } \partial \Omega(t) \\
(1, \mathbf{v}) \text { is tangent to }(t, \partial \Omega(t))
\end{array}\right.
$$

$\mathbf{v}$ is the fluid velocity, $P$ is the fluid pressure.

When surface tension is zero, the motion can be subject to the Taylor instability

- Taylor sign condition:

$$
\begin{equation*}
-\frac{\partial P}{\partial \mathbf{n}} \geq 0 \tag{2}
\end{equation*}
$$

on the interface $\partial \Omega(t)$. $\mathbf{n}$ is the unit outward normal to the fluid domain $\Omega(t)$.

- G. I. Taylor (1949)
- Strong Taylor sign condition:

$$
\begin{equation*}
-\frac{\partial P}{\partial \mathbf{n}} \geq c_{0}>0 \tag{3}
\end{equation*}
$$

## History

Newton, Stokes, Levi-Civita, G.I.Taylor.....

## Local wellposedness in Sobolev spaces

- Nalimov (1974), Yoshihara (1982), W. Craig (1985): 2D, local wellposedness for small Sobolev data;
- S. Wu (1997, 99): 2D and 3D, Local wellposedness for arbitrary data in Sobolev spaces $H^{s}$, for $s \geq 4$.
Proved that the strong Taylor sign condition always holds, i.e.

$$
\begin{equation*}
-\frac{\partial P}{\partial \mathbf{n}} \geq c_{0}>0 \tag{4}
\end{equation*}
$$

for $C^{1, \gamma}, \gamma>0$ interfaces.

- Christodoulou \& Lindblad (2000), Iguchi(2001), Ogawa \& Tani (2002), Ambrose \& Masmoudi(2005), D. Lannes (2005), Lindblad (2005), Coutand \& Shkoller (2007), P. Zhang \& Z. Zhang (2007), Shatah \& Zeng (2008)
Local wellposedness with additional effects: nonzero surface tension, finite depth, nonzero vorticity, assuming the strong Taylor sign condition holds.


## Global behavior for small, smooth and sufficiently localized

 data: - Gravity-WW- S. Wu (2009), S. Wu (2011): almost global for 2-D, global well-posedness for 3-D;
- Germain, Masmoudi \& Shatah (2012): global well-posedness for 3-D
- Ionescu \& Pusateri (2015), Alazard \& Delort (2015): global existence and modified scattering for 2-D;
- Hunter, Ifrim \& Tataru (2016), Ifrim \& Tataru (2016), Ai, Ifrim \& Tataru (2019, 2020): lowered the regularity threshold;
- main ideas: 1 . after suitable change of variables, the water wave equation has no quadratic nonlinear terms; 2. use the dispersive decay property for sufficiently localized solutions to get extended lifespan.
- If the data is smooth and of size $\epsilon$, and non-localized, the solution exists on time of order $O\left(\epsilon^{-2}\right)$.
- The main mechanism is that there are no 3-waves resonant interactions.


## Question:

Is it possible to further remove the cubic nonlinearities of the gravity-WW using a normal form transformation?

## The Hamiltonian point of view, the periodic case

- Zakharov (1968): formulated 2d water wave equations as a Hamiltonian system
- Dyachenko \& Zakharov (1994): no 3-wave interactions, all 4-wave interaction coefficients vanish on the non-trivial resonant manifold
- Craig \& Wolfolk (1995): formal derivation of the Birkhoff normal form transformation of order 4
- Craig \& Sulem (2016): studied mapping properties
- Berti, Feola \& Pusateri (2018): existence for time of order $O\left(\epsilon^{-3}\right)$ for periodic small, smooth data of size $\epsilon$.

Dyachenko \& Zakharov (1994):

- No 3-wave resonant interactions;
- After the Birkhoff normal form procedure, the Hamiltonian

$$
H \circ \Phi=H^{(2)}+H^{(4)}+\ldots .
$$

- There are two types of 4-wave resonant interactions:
- the trivial ones,
- the Benjamin-Feir resonances,
- there is no cancelations on the trivial ones,
- the coefficients in $H^{(4)}$ vanish on the Benjamin-Feir resonances.
- Berti, Feola, Pusateri (2018): bounded, invertible Birkhoff normal forms; non-symplectic, non-explicit;
- For the whole line case, one also need to deal with near resonances.
- The computations of Dyachenko \& Zakharov, Craig \& Wolfolk, Berti, Feola \& Pusateri are all carried out in the Fourier space using tools such as the Birkhoff normal forms from dynamical system.
- Question: how does this fact manifest, explicitly and naturally, in the physical space?

How do we solve the water wave equation (1)?

- A usual approach is to reduce from (1) to an equation on the interface, and study the interface equation.
- Recover $\mathbf{v}$ from its value on the interface $\partial \Omega(t)$ by solving $\Delta \mathbf{v}=0, \quad$ in $\Omega(t) ;$
- We consider the 2 d case. Use the Riemann mapping variable.
- We describe the approach in Wu $(1997,2009,2018)$


## The surface equation in Lagrangian coordinates

- We identify $(x, y)=x+i y$;
- The free surface

$$
\partial \Omega(t): z=z(\alpha, t)
$$

$\alpha \in \mathbb{R} ; \alpha$ is the Lagrangian coordinate.

- $z_{t}=z_{t}(\alpha, t)$ velocity, $z_{t t}=z_{t t}(\alpha, t)$ acceleration,
- the gravity $(0,-g)=(0,-1)=-i$.
- $-\nabla P=-\frac{\partial P}{\partial \mathbf{n}} \mathbf{n}:=i \mathfrak{a} z_{\alpha}$,
$\mathbf{n}=\frac{i z_{\alpha}}{\left|z_{\alpha}\right|}, \mathfrak{a}=-\frac{\partial P}{\partial \mathbf{n}} \frac{1}{\left|z_{\alpha}\right|} ;$
- $\bar{z}_{t}$ boundary value of the holomorphic function $\overline{\mathbf{v}}$.

$$
\begin{cases}\mathbf{v}_{t}+(\mathbf{v} \cdot \nabla) \mathbf{v}=(\mathbf{0},-1)-\nabla P \quad \text { in } \Omega(t)  \tag{5}\\ \operatorname{div} \mathbf{v}=0, \quad \operatorname{curl} \mathbf{v}=0, & \text { in } \Omega(t) \\ P=0, & \text { on } \partial \Omega(t)\end{cases}
$$

## Equation of the free surface:

$$
\left\{\begin{array}{l}
z_{t t}+i=i \mathfrak{a} z_{\alpha}  \tag{6}\\
\overline{z_{t}}=\mathfrak{H} \overline{z_{t}}
\end{array}\right.
$$

where $\mathfrak{H}$ is the Hilbert transform,

$$
\mathfrak{H} f(\alpha)=\frac{1}{\pi i} \int \frac{z_{\beta}(\beta, t)}{z(\alpha, t)-z(\beta, t)} f(\beta) d \beta
$$

## The surface equation in the Riemann mapping framework

Let

$$
\Psi=\Psi(\cdot, t): P_{-} \rightarrow \Omega(t)
$$

be the Riemann mapping satisfying $\lim _{z^{\prime} \rightarrow \infty} \Psi_{z^{\prime}}\left(z^{\prime}, t\right)=1$; here $P_{-}$is the lower half plane.
Let

- $Z\left(\alpha^{\prime} ; t\right):=\Psi\left(\alpha^{\prime} ; t\right) \quad$ - interface;
- $Z(h(\alpha, t), t)=z(\alpha, t), b=h_{t} \circ h^{-1}$;
- $h(\alpha, t)=\alpha^{\prime}$;
- $Z_{t}:=D_{t} Z=v\left(Z\left(\alpha^{\prime} ; t\right) ; t\right) \quad$ - velocity;
- $Z_{t t}:=D_{t} Z_{t} \quad$ - acceleration;
- $D_{t}:=\partial_{t}+b \partial_{\alpha^{\prime}} \quad$ - the material derivative;
- $\partial_{\alpha^{\prime}} Z:=Z_{, \alpha^{\prime}}, Z_{t t, \alpha^{\prime}}=\partial_{\alpha^{\prime}}\left\{Z_{t t}\right\}$, etc.


## Surface equation in Riemann mapping coordinate

## Equation of the free surface:

$$
\left\{\begin{array}{c}
Z_{t t}+i=\frac{i A_{1}}{\bar{Z}_{, \alpha^{\prime}}}, \quad\left(Z_{t t}=D_{t} Z_{t}=\left(\partial_{t}+b \partial_{\alpha}\right) Z_{t}\right) \\
(I-\mathbb{H}) \bar{Z}_{t}=0, \quad(I-\mathbb{H})\left(\frac{1}{Z_{, \alpha^{\prime}}}-1\right)=0 \\
A_{1}=1-\operatorname{Im}\left[Z_{t}, \mathbb{H}\right] \bar{Z}_{t, \alpha^{\prime}} \geq 1  \tag{8}\\
b:=h_{t} \circ h^{-1}=\operatorname{Re}(I-\mathbb{H}) \frac{Z_{t}}{Z_{, \alpha^{\prime}}}
\end{array}\right.
$$

- $Z_{t}$ - velocity, $\frac{1}{Z_{, \alpha^{\prime}}}$ - fluid domain,
- $-\left|Z_{, \alpha^{\prime}}\right| \frac{\partial P}{\partial \mathbf{n}}=A_{1} \geq 1$;

$$
\mathbb{H} f\left(\alpha^{\prime}\right)=\frac{1}{\pi i} \int \frac{1}{\alpha^{\prime}-\beta^{\prime}} f\left(\beta^{\prime}\right) d \beta^{\prime} .
$$

## The quasilinear equation in Riemann mapping coordinate:

- Taking one time derivative (material derivative) to (6), we get a quasilinear equation:

$$
\left(\partial_{t}^{2}+i \mathfrak{a} \partial_{\alpha}\right) \bar{z}_{t}=-i \mathfrak{a}_{t} \bar{z}_{\alpha} \quad\left(=\frac{\mathfrak{a}_{t}}{\mathfrak{a}}\left(\bar{z}_{t t}-i\right)\right) .
$$

- In Riemann mapping variable it is:

$$
\begin{equation*}
\left(D_{t}^{2}+i \frac{A_{1}}{\left|Z_{, \alpha^{\prime}}\right|^{2}} \partial_{\alpha^{\prime}}\right) \bar{Z}_{t}=\frac{\mathfrak{a}_{t}}{\mathfrak{a}} \circ h^{-1}\left(\bar{Z}_{t t}-i\right) \tag{9}
\end{equation*}
$$

where

$$
\begin{equation*}
\frac{\mathfrak{a}_{t}}{\mathfrak{a}} \circ h^{-1}=\text { quadratic } \tag{10}
\end{equation*}
$$

$\mathcal{P} \bar{Z}_{t}=$ quadratic, lower order terms.

## The normal form transformation in Wu (2009)

- Let $\phi$ be the velocity potential, i.e. $\mathbf{v}=\nabla \phi$,
- Let $\psi=\phi(z(\alpha, t), t)$
- $\Lambda=(I-\mathfrak{H}) \psi, \Pi=(I-\mathfrak{H})(z-\bar{z})$ satisfy equations:

$$
\left(\partial_{t}^{2}-i \mathfrak{a} \partial_{\alpha}\right) \Lambda=\text { cubic }, \quad\left(\partial_{t}^{2}-i \mathfrak{a} \partial_{\alpha}\right) \Pi=\text { cubic }
$$

- a coordinate change given by

$$
\kappa=2 \Re z-h
$$

removes the quadratic nonlinearities on the left hand side:

$$
\left(\partial_{t}^{2}-i \partial_{\alpha}\right)\left(\Lambda \circ \kappa^{-1}\right)=\text { cubic }, \quad\left(\partial_{t}^{2}-i \partial_{\alpha}\right)\left(\Pi \circ \kappa^{-1}\right)=\text { cubic } .
$$

- The basic energy functional: for $\theta$ holomorphic,

$$
E(\theta, t)=\int \frac{1}{\mathfrak{a}}\left|\partial_{t} \theta\right|^{2}+i \partial_{\alpha} \theta \bar{\theta} d \alpha
$$

$$
\frac{d}{d t} E\left(\partial^{j} \Lambda, t\right)=\text { quartic, } \quad \text { same for } \partial^{j} \Pi .
$$

- Existence of solution for time of order $O\left(\epsilon^{-2}\right)$ for data of size $\epsilon$.
- A further use of the method of vector fields yields the almost global existence result in Wu (2009).
- Similar quartic estimate played key roles in Ionescu \& Pusateri (2015), Alazard \& Delort (2015), Hunter, Ifrim \& Tataru (2016)......;
- The mechanism behind is the absence of 3 -wave interactions.


## Question:

Is it possible to construct a sequence of energy functionals $\mathfrak{E}_{j}(t)$, so that

$$
\frac{d}{d t} \mathfrak{E}_{j}(t)=\text { quintic? }
$$

- The construction works for both the whole line and the periodic cases.


## Results on the structure of the water wave equation

- Begin with reconstructing a quartic energy functional sequence.
- Define: $\mathbb{P}_{H}=\frac{1}{2}(I+\mathbb{H}), \mathbb{P}_{A}=\frac{1}{2}(I-\mathbb{H})$
- Begin with

$$
\begin{gather*}
Q:=(I+\mathbb{H})\left(\psi \circ h^{-1}\right), \\
\left.\left(D_{t} \mathbb{P}_{H} D_{t}+i \frac{1}{\left|Z_{, \alpha^{\prime}}\right|^{2}} \partial_{\alpha^{\prime}}\right) Q=i \mathbb{P}_{A}\left(Z_{t}\left(1-\frac{1}{Z_{, \alpha^{\prime}}}\right)\right)+\bar{Z}_{t}\left(\frac{1}{\bar{Z}_{, \alpha^{\prime}}}-1\right)\right) . \tag{11}
\end{gather*}
$$

- Let

$$
\begin{gather*}
\Theta^{(0)}:=Q, \quad \Theta^{(j)}:=\left(\mathbb{P}_{H} D_{t}\right)^{j} Q  \tag{12}\\
\left(D_{t} \mathbb{P}_{H} D_{t}+i \frac{1}{\left|Z_{, \alpha^{\prime}}\right|^{2}} \partial_{\alpha^{\prime}}\right) \Theta^{(j)}=: G^{(j)} \tag{13}
\end{gather*}
$$

- $\mathbb{P}_{H} G^{(0)}=0$.
- Derive a formula for $\mathbb{P}_{H}\left(G^{(j)}\right)$, - it is cubic with symmetric structures.


## Proposition (energy identity)

Let $\Theta_{1}, \Theta_{2}$ be holomorphic, Define

$$
\begin{equation*}
E(t)=\Re\left(\int i \partial_{\alpha^{\prime}} \Theta_{2} \overline{\mathbb{P}_{H} D_{t} \Theta_{1}} d \alpha^{\prime}-\int i \partial_{\alpha^{\prime}} \Theta_{1} \overline{\mathbb{P}_{H} D_{t} \Theta_{2}} d \alpha^{\prime}\right) . \tag{14}
\end{equation*}
$$

Then

$$
\begin{equation*}
\frac{d}{d t} E(t)=\Re\left(\int i \partial_{\alpha^{\prime}} \Theta_{2} \overline{\left(\mathbb{P}_{H} G_{1}\right)} d \alpha^{\prime}-\int i \partial_{\alpha^{\prime}} \Theta_{1} \overline{\left(\mathbb{P}_{H} G_{2}\right)} d \alpha^{\prime}\right) . \tag{15}
\end{equation*}
$$

where $G_{k}:=\left(D_{t} \mathbb{P}_{H} D_{t}+i \frac{1}{\left|Z_{, \alpha^{\prime}}\right|^{2}} \partial_{\alpha^{\prime}}\right) \Theta_{k}$, for $k=1,2$.

- Let

$$
\begin{equation*}
E_{j}(t)=\Re\left(\int i \partial_{\alpha^{\prime}} \Theta^{(j+1)} \overline{\Theta^{(j+1)}} d \alpha^{\prime}-\int i \partial_{\alpha^{\prime}} \Theta^{(j)} \overline{\Theta^{(j+2)}} d \alpha^{\prime}\right) \tag{16}
\end{equation*}
$$

- From (15),

$$
\begin{aligned}
& \frac{d}{d t} E_{j}(t)=\Re\left(\int i \partial_{\alpha^{\prime}} \Theta^{(j+1)} \overline{\mathbb{P}_{H} G^{(j)}} d \alpha^{\prime}-\int i \partial_{\alpha^{\prime}} \Theta^{(j)} \overline{\mathbb{P}_{H} G^{(j+1)}} d \alpha^{\prime}\right) ; \\
& 2\left(\mathbb{P}_{H} G^{(I+1)}-\mathbb{P}_{H} D_{t} \mathbb{P}_{H} G^{(I)}\right) \\
& \quad=\mathbb{P}_{H}\left(\frac{1}{\bar{Z}_{, \alpha^{\prime}}}\left(<\bar{Z}_{t}, i \frac{1}{\bar{Z}_{, \alpha^{\prime}}}, D_{\alpha^{\prime}} \Theta^{(I)}>+<-i \frac{1}{Z_{, \alpha^{\prime}}}, Z_{t}, D_{\alpha^{\prime}} \Theta^{(I)}>\right)\right), \\
& \bullet<f, g, h>=\frac{1}{\pi i} \int \frac{\left(f\left(\alpha^{\prime}\right)-f\left(\beta^{\prime}\right)\right)\left(g\left(\alpha^{\prime}\right)-g\left(\beta^{\prime}\right)\right)\left(h\left(\alpha^{\prime}\right)-h\left(\beta^{\prime}\right)\right)}{\left(\alpha^{\prime}-\beta^{\prime}\right)^{2}} d \beta^{\prime} .
\end{aligned}
$$

- $\frac{d}{d t} E_{j}(t)$ is quartic in terms of only the derivatives of $\frac{1}{Z_{, \alpha^{\prime}}}$ and $Z_{t}$;


## Removing the quartic terms

$$
-i \frac{1}{Z_{, \alpha^{\prime}}}+i=\bar{Z}_{t t}+\text { quadratic, } \quad D_{\alpha^{\prime}} \Theta^{(k)}=D_{t}^{k} \bar{Z}_{t}+\text { quadratic }
$$

- Derive an energy identity which moves the $D_{t}$ derivatives from factors to factors:
- Provided $\mathcal{P} f, \mathcal{P g}, \mathcal{P} h, \mathcal{P q}$ are quadratic,

$$
\begin{align*}
& \frac{d}{d t} \iint \frac{\bar{f} \mathfrak{D}_{t}(g \bar{h} q)-\left(\mathfrak{D}_{t} \bar{f}\right) g \bar{h} q}{\left(\alpha^{\prime}-\beta^{\prime}\right)^{2}} d \alpha^{\prime} d \beta^{\prime} \\
& =2 \iint \frac{\bar{f} \mathfrak{D}_{t}(g \bar{h}) \mathfrak{D}_{t} q+\bar{f} \mathfrak{D}_{t}\left(g \mathfrak{D}_{t} \bar{h}\right) q}{\left(\alpha^{\prime}-\beta^{\prime}\right)^{2}} d \alpha^{\prime} d \beta^{\prime}+\text { quintic, } \tag{17}
\end{align*}
$$

- Let $\theta=\bar{Z}_{t}\left(\alpha^{\prime}, t\right)-\bar{Z}_{t}\left(\beta^{\prime}, t\right)$,
- let $\mathfrak{D}_{t}=\partial_{t}+b\left(\alpha^{\prime}, t\right) \partial_{\alpha^{\prime}}+b\left(\beta^{\prime}, t\right) \partial_{\beta^{\prime}}$,

$$
\begin{aligned}
C_{2, j} & =\frac{1}{4 \pi} \sum_{k=0}^{j-1}(-1)^{k} \iint \frac{\left(D_{t}^{j} Z_{t} \mathfrak{D}_{t}-D_{t}^{j+1} Z_{t}\right) \theta \mathfrak{D}_{t}^{k} \bar{\theta} \mathfrak{D}_{t}^{j-k-1} \theta}{\left(\alpha^{\prime}-\beta^{\prime}\right)^{2}} d \beta^{\prime} d \alpha^{\prime} \\
& +\frac{1}{4 \pi}(-1)^{j} \iint D_{t}^{j} Z_{t} \frac{\theta \mathfrak{D}_{t}^{j} \bar{\theta} \theta}{\left(\alpha^{\prime}-\beta^{\prime}\right)^{2}} d \beta^{\prime} d \alpha^{\prime} .
\end{aligned}
$$

$$
\begin{align*}
& C_{1, j}=\frac{1}{2 \pi} \sum_{l=0}^{j-1} \sum_{k=0}^{l} \iint \frac{\left(D_{t}^{j} Z_{t} \mathfrak{D}_{t}-D_{t}^{j+1} Z_{t}\right) \mathfrak{D}_{t}^{I-k}\left(\mathfrak{D}_{t}^{k} \theta \bar{\theta} \mathfrak{D}_{t}^{j-I-1} \theta\right)}{\left(\alpha^{\prime}-\beta^{\prime}\right)^{2}} d \beta^{\prime} d \alpha^{\prime} \\
& +\frac{1}{4 \pi} \sum_{l=0}^{j-2} \sum_{k=0}^{j-I-2}(-1)^{k} \iint \frac{\left(D_{t}^{j} Z_{t} \mathfrak{D}_{t}-D_{t}^{j+1} Z_{t}\right) \mathfrak{D}_{t}^{1+\prime} \theta \mathfrak{D}_{t}^{k} \bar{\theta} \mathfrak{D}_{t}^{j-I-2-k} \theta}{\left(\alpha^{\prime}-\beta^{\prime}\right)^{2}} d \beta^{\prime} d \alpha^{\prime} \\
& -\frac{1}{8 \pi} \sum_{l=0}^{j-2} \sum_{k=0}^{j-I-2}(-1)^{k} \iint \frac{\left(\theta \mathfrak{D}_{t}-\mathfrak{D}_{t} \theta\right) \mathfrak{D}_{t}^{j-I-1} \bar{\theta} \mathfrak{D}_{t}^{j-k-1} \theta \mathfrak{D}_{t}^{k+I+1} \bar{\theta}}{\left(\alpha^{\prime}-\beta^{\prime}\right)^{2}} d \beta^{\prime} d \alpha^{\prime} \\
& +\frac{1}{2 \pi} \sum_{l=0}^{j-1} \iint D_{t}^{j} Z_{t} \frac{\mathfrak{D}_{t}^{j-I-1} \theta \bar{\theta} \mathfrak{D}_{t}^{1+\prime} \theta}{\left(\alpha^{\prime}-\beta^{\prime}\right)^{2}} d \beta^{\prime} d \alpha^{\prime}, \tag{19}
\end{align*}
$$

## Main result on the quartic integrability of WWE

## Theorem

Let

$$
\begin{equation*}
\mathfrak{E}_{j}(t)=E_{j}(t)-\Re\left(\int i \partial_{\alpha^{\prime}} \Theta^{(j)} \overline{\mathbb{P}_{H} G^{(j)}} d \alpha^{\prime}+C_{1, j}(t)+C_{2, j}(t)\right) \tag{20}
\end{equation*}
$$

Then

$$
\begin{equation*}
\frac{d}{d t} \mathfrak{E}_{j}(t)=\text { quintic } \tag{21}
\end{equation*}
$$

with desirable structures.

- $\mathfrak{E}_{j}(t)$ controls only the spatial derivatives of $\frac{1}{Z_{, \alpha^{\prime}}}$ and $Z_{t}$, waves with large steepness and velocity can be small in $\mathfrak{E}_{j}(t)$ for $j \geq 2$;
- $\frac{d}{d t} \mathfrak{E}_{j}(t)$ is quintic in terms of the spatial derivatives of $\frac{1}{Z_{, \alpha^{\prime}}}$ and $Z_{t}$.


## Scaling law

- If $\left(\bar{Z}_{t}, Z\right)$ is a solution of (7)-(8), then

$$
\begin{equation*}
\left(\bar{Z}_{t}^{\lambda}, Z^{\lambda}\right):=\left(\lambda^{-1 / 2} \bar{Z}_{t}\left(\lambda \alpha^{\prime}, \lambda^{1 / 2} t\right), \lambda^{-1} Z\left(\lambda \alpha^{\prime}, \lambda^{1 / 2} t\right)\right) \tag{22}
\end{equation*}
$$

is also a solution of (7)-(8).

- Scaling invariant norms:

$$
\begin{gathered}
\left\|\frac{1}{Z_{, \alpha^{\prime}}}-1\right\|_{\dot{H}^{1 / 2}(\mathbb{R})}, \quad\left\|\bar{Z}_{t, \alpha^{\prime}}\right\|_{L^{2}(\mathbb{R})} \\
\left\|\frac{1}{Z_{, \alpha^{\prime}}}-1\right\|_{L^{\infty}(\mathbb{R})}
\end{gathered}
$$

- Let

$$
\begin{align*}
L(t)= & \left\|\frac{1}{Z_{, \alpha^{\prime}}}(t)\right\|_{\dot{H}^{1 / 2}(\mathbb{R})}+\left\|\bar{Z}_{t, \alpha^{\prime}}(t)\right\|_{L^{2}(\mathbb{R})} \\
& +\left\|\partial_{\alpha^{\prime}} \frac{1}{Z_{, \alpha^{\prime}}}(t)\right\|_{\dot{H}^{1 / 2}(\mathbb{R})}+\left\|\partial_{\alpha^{\prime}}^{2} \bar{Z}_{t}(t)\right\|_{L^{2}(\mathbb{R})} \tag{23}
\end{align*}
$$

## Theorem

1. Let $J \geq 2$. Assume that the initial data
$\left(\bar{Z}_{t}(0), \frac{1}{Z_{, \alpha^{\prime}}}(0)\right) \in \cap_{\frac{1}{2} \leq s \leq J} \dot{H}^{s}(\mathbb{R}) \times \dot{H}^{s-\frac{1}{2}}(\mathbb{R})$. Then there are constants $m_{0}>0$, and $\varepsilon_{0}>0$, such that for all $0<\varepsilon \leq \varepsilon_{0}$, if the data satisfies

$$
\begin{equation*}
L(0) \leq \varepsilon, \quad\left\|\frac{1}{Z_{, \alpha^{\prime}}}(0)-1\right\|_{L^{\infty}}<1, \quad E_{1}(0) E_{3}(0) \leq m_{0}^{2} \tag{24}
\end{equation*}
$$

then the lifespan of the unique classical solution for the $2 d$ water wave equation (1) is at least of order $O\left(\varepsilon^{-3}\right)$. During this time, the solution is as regular as the initial data and $L(t)$ remains small.

## Theorem (continued)

If instead of (24) the data satisfies

$$
\begin{array}{r}
\left\|\frac{1}{Z_{, \alpha^{\prime}}}(0)\right\|_{\dot{H}^{1 / 2}(\mathbb{R})}+\left\|\bar{Z}_{t, \alpha^{\prime}}(0)\right\|_{L^{2}(\mathbb{R})} \leq \varepsilon \\
\left\|\frac{1}{Z_{, \alpha^{\prime}}}(0)-1\right\|_{L^{\prime}}<1, \quad E_{1}(0) E_{3}(0) \leq m_{0}^{2} \tag{25}
\end{array}
$$

then the lifespan of the unique classical solution for the $2 d$ water wave equation (1) is at least of order $O\left(\varepsilon^{-5 / 2}\right)$. During this time, the solution is as regular as the initial data.

Remark: $\left\|\frac{1}{Z_{, \alpha^{\prime}}}(0)\right\|_{\dot{H}^{1 / 2}(\mathbb{R})}+\left\|\bar{Z}_{t, \alpha^{\prime}}(0)\right\|_{L^{2}(\mathbb{R})}$ is scaling invariant.

## Remarks

- $E_{1}(t) \approx\left\|\frac{1}{Z_{, \alpha^{\prime}}}(t)-1\right\|_{L^{2}(\mathbb{R})}^{2}+\left\|\bar{Z}_{t}(t)\right\|_{\dot{H}^{1 / 2}(\mathbb{R})^{\prime}}^{2}$
- $E_{3}(t) \approx\left\|\frac{1}{Z_{, \alpha^{\prime}}}(t)\right\|_{\dot{H}^{1}(\mathbb{R})}^{2}+\left\|\bar{Z}_{t, \alpha^{\prime}}(t)\right\|_{\dot{H}^{1 / 2}(\mathbb{R})^{\prime}}^{2}$
- $E_{1}(t) E_{3}(t)$ is scaling invariant,
- Sobolev embedding: $\left\|\frac{1}{Z_{, \alpha^{\prime}}}(t)-1\right\|_{L^{\infty}}^{2} \leq c_{0} E_{1}(t) E_{3}(t)$,
- $E_{1}(t) E_{3}(t)$ remains controlled for time of order $O\left(\varepsilon^{-3}\right)$,
- If $\left\|_{Z_{, \alpha^{\prime}}}^{1}(0)-1\right\|_{L^{\infty}} \leq 1-2 \delta$, then $\left\|\frac{1}{Z_{, \alpha^{\prime}}}(t)-1\right\|_{L^{\infty}} \leq 1-\delta$ for time of order $O\left(\varepsilon^{-3}\right)$.
- $m_{0}>0$ need not be small, $0<\delta<1$ is arbitrary.


## Remarks

- Part 2 of the Theorem is a consequence of part 1 by a scaling argument.
- The rescaled data $\left(\bar{Z}_{t}^{\varepsilon}(0), Z^{\varepsilon}(0)\right)$ satisfies

$$
\left\|\partial_{\alpha^{\prime}} \frac{1}{Z_{, \alpha^{\prime}}^{\varepsilon}}(0)\right\|_{\dot{H}^{1 / 2}}+\left\|\partial_{\alpha^{\prime}}^{2} \bar{Z}_{t}^{\varepsilon}(0)\right\|_{L^{2}}=\varepsilon\left\|\partial_{\alpha^{\prime}} \frac{1}{Z_{, \alpha^{\prime}}}(0)\right\|_{\dot{H}^{1 / 2}}+\varepsilon\left\|\partial_{\alpha^{\prime}}^{2} \bar{Z}_{t}(0)\right\|_{L^{2}} .
$$

- The rescaled solution $\left(\bar{Z}_{t}^{\varepsilon}(t), Z^{\varepsilon}(t)\right)$ has lifespan of order $O\left(\varepsilon^{-3}\right)$ implies that the solution $\left(\bar{Z}_{t}(t), Z(t)\right)$ has lifespan of order $O\left(\varepsilon^{-5 / 2}\right)$.
- The lifespan of the solution is in fact of order $O\left(\varepsilon^{-3+\frac{1}{2 J-2}}\right)$, under the assumption of part 2.
- The interface $Z=Z\left(\alpha^{\prime}, t\right)$ is a graph during the lifespan of the solution.


## Main ideas

- Use the quintic energy functionals $\mathfrak{E}_{j}(t)$,

$$
\begin{gathered}
\mathfrak{E}_{j}(t) \approx\left\|\frac{1}{Z_{, \alpha^{\prime}}}(t)-1\right\|_{\dot{H}^{\frac{j-1}{2}}(\mathbb{R})}^{2}+\left\|\bar{Z}_{t}(t)\right\|_{\dot{H}^{\frac{j}{2}}(\mathbb{R})}^{2} \\
\frac{d}{d t} \mathfrak{E}_{j}(t)=O\left(\epsilon^{5}\right), \quad \text { for } \quad 2 \leq j \leq 4 \\
\frac{d}{d t}\left(\mathfrak{E}_{1}(t) \mathfrak{E}_{3}(t)\right)=O\left(\epsilon^{3}\right) \mathfrak{E}_{1}(t) \mathfrak{E}_{3}(t),
\end{gathered}
$$

- provided

$$
L(t) \leq \epsilon, \quad\left\|\frac{1}{Z_{, \alpha^{\prime}}}(t)-1\right\|_{L^{\infty}} \leq 1-\delta ;
$$

$$
0<\epsilon \leq \epsilon_{0}(\delta)
$$

Some further Remarks:

- Similar calculations apply to a variety of free boundary problems, and for some we can derive higher order integrability, of quartic or cubic orders...
- A recent work of Deng, lonescu, Pusateri (2022): quartic integrability, and longer time existence by using dispersive property.

Thank you!

